# Spatio-temporal Transfer Function Conditions of Positive Realness for Translation Invariant Lattice Networks of Interacting Linear Systems\*

Igor G. Vladimirov<sup>†</sup>, Ian R. Petersen<sup>†</sup>

Abstract—This paper is concerned with networks of interacting linear systems at sites of a multidimensional lattice. The systems are governed by linear ODEs with constant coefficients driven by external inputs, and their internal dynamics and coupling with the other component systems are translation invariant. Such systems occur, for example, in finite-difference models of large-scale flexible structures manufactured from homogeneous materials. Using the spatio-temporal transfer function of this translation invariant network, we establish conditions for its positive realness in the sense of energy dissipation. The latter is formulated in terms of block Toeplitz bilinear forms of the input and output variables of the composite system. We also discuss quadratic stability of the network in isolation from the environment and phonon theoretic dispersion relations.

Index Terms—Translation invariant networks, spatiotemporal frequency domain, energy balance relations.

MSC Codes — 93C05, 90B10, 37L60, 37K05, 93C80.

#### I. INTRODUCTION

Complex physical systems can be viewed as a large number of relatively simple subsystems whose collective behaviour is a cumulative effect of their interaction rather than a particular individual structure. Spatially homogeneous states of matter are modelled as identical building blocks which interact with each other in a translationally invariant fashion. A natural example of large-scale composite systems with translational symmetry is provided by crystalline solids, where spatially periodic arrangements of constituent particles result from their interaction and play an important role in their thermodynamic and mechanical properties (including the heat transfer and wave propagation) studied in the phonon theory [13].

Modern engineering exploits translation invariant interconnections in drone swarming, vehicle platooning and artificially fabricated metamaterials [15], such as split ring resonator arrays with unusual electrodynamic characteristics (a negative refraction index). Nontrivial input-output properties of such networks of systems (natural or artificial) are not merely a "sum" of individual internal dynamics of their constituent blocks and come from a specific structure of energy flows through the translation invariant interaction.

The energy balance relations, which reflect the energy conservation and dissipation in isolated and open systems (for example, due to electrical resistance and mechanical friction), significantly affect the behaviour of physical systems and play an increasingly important role in control design [7], [8], [14]. These equations involve the internal energy and the work done on the system (which are represented in the dissipativity theory [18] in terms of storage and supply rate functions). Work is modelled by using a bilinear form of the input and output variables, which are interpreted as the generalised force and velocity respectively. For linear time-invariant systems with a finite-dimensional internal state, the properties of being passive, positive real or negative imaginary (in the case of position variables instead of the velocity as the output) admit criteria in the form of linear matrix inequalities for the transfer functions in the frequency domain or the state-space matrices themselves [10], [19].

The present paper is concerned with similar conditions for networks of interacting linear systems at sites of a multidimensional lattice. The composite system is governed by an infinite set of linear ODEs with constant coefficients driven by external inputs, and their internal dynamics and coupling with the other component systems are translation invariant. These ODEs have block Toeplitz state-space matrices and can be represented in the spatio-temporal frequency domain by using appropriately modified transfer functions of several variables. Such systems arise, for example, as finitedifference approximations of PDEs for large-scale flexible structures made of spatially homogeneous materials. Using the spatio-temporal transfer function of this translation invariant network, we establish conditions for its positive realness in the sense of energy dissipation. The latter is formulated in terms of block Toeplitz bilinear forms of the input and output variables of the composite system. The multivariate Laplace and Fourier transform techniques, which are used for this purpose, are similar to those for distributed control systems in the classical and quantum settings [1], [2], [3], [12], [16].

The paper is organised as follows. Section II describes the class of translation invariant networks under consideration. Section III represents the network dynamics in terms of the spatial Fourier transforms of its signals. Section IV discusses energy balance relations in the case of bilinear supply rate and quadratic storage functions. Section V establishes conditions for passivity of the network in terms of its spatio-temporal transfer function, and also discusses quadratic stability bounds for a dissipative network in isolation from the environment. Section VI considers phonon theoretic dispersion relations for the isolated network. Section VII

<sup>\*</sup>This work is supported by the Australian Research Council under grant DP160101121.

<sup>†</sup>Research School of Engineering, College of Engineering and Computer Science, Australian National University, ACT 2601, Canberra, Australia. igor.g.vladimirov@gmail.com, ir.petersen@gmail.com.

provides concluding remarks. Proofs are given in the full version of this paper in [17].

### II. TRANSLATION INVARIANT NETWORKS

We consider a translation invariant network of coupled linear systems at sites of the v-dimensional integer lattice  $\mathbb{Z}^v$ . For any spatial index  $k \in \mathbb{Z}^v$ , the kth system is endowed with an  $\mathbb{R}^n$ -valued vector  $x_k$  of time-varying state variables (for example, the generalised positions and velocities). Associated with the kth lattice site are vectors  $u_k$  and  $y_k$  of external input and output variables which take values in  $\mathbb{R}^m$  and  $\mathbb{R}^r$ , respectively, and also vary in time (unless indicated otherwise, vectors are organised as columns). The states and outputs of these systems are governed by an infinite set of coupled ODEs

$$\dot{x}_{j} = \sum_{k \in \mathbb{Z}^{N}} (A_{j-k} x_{k} + B_{j-k} u_{k}), \tag{1}$$

$$y_j = \sum_{k \in \mathbb{Z}^y} (C_{j-k} x_k + D_{j-k} u_k)$$
 (2)

for all  $j \in \mathbb{Z}^v$ , where  $\dot{(})$  is the time derivative (the time arguments are often omitted for brevity). Their right-hand sides are organised as convolutions, with the matrices  $A_\ell \in \mathbb{R}^{n \times n}$ ,  $B_\ell \in \mathbb{R}^{n \times m}$ ,  $C_\ell \in \mathbb{R}^{r \times n}$ ,  $D_\ell \in \mathbb{R}^{r \times m}$  depending on the relative location  $\ell \in \mathbb{Z}^v$  of the lattice sites in accordance with the translation invariance of the individual dynamics of the systems and their coupling. By assembling the inputs, states and outputs into the infinite-dimensional vectors  $u := (u_k)_{k \in \mathbb{Z}^v}$ ,  $x := (x_k)_{k \in \mathbb{Z}^v}$ ,  $y := (y_k)_{k \in \mathbb{Z}^v}$ , the set of ODEs (1) and (2) can be written as

$$\dot{x} = Ax + Bu,\tag{3}$$

$$y = Cx + Du, (4)$$

where the matrices  $A:=(A_{j-k})_{j,k\in\mathbb{Z}^{\nu}},\ B:=(B_{j-k})_{j,k\in\mathbb{Z}^{\nu}},$   $C:=(C_{j-k})_{j,k\in\mathbb{Z}^{\nu}},\ D:=(D_{j-k})_{j,k\in\mathbb{Z}^{\nu}}$  are block Toeplitz in the sense of the additive group structure of the lattice  $\mathbb{Z}^{\nu}$ . The ODE (3) is understood as a Volterra integral equation (of the second kind)

$$x(t) = \int_0^t (Ax(\tau) + Bu(\tau)) d\tau$$
 (5)

whose solution is given by

$$x(t) = e^{tA}x(0) + \int_0^t e^{(t-\tau)A}Bu(\tau)d\tau, \qquad t \geqslant 0.$$
 (6)

For completeness, we note that (3)–(6) can be endowed with a rigorous meaning as follows. To this end, the state-space matrices in (1) and (2) are assumed to be square summable:

$$\sum_{\ell \in \mathbb{Z}^{N}} \left\| \begin{bmatrix} A_{\ell} & B_{\ell} \\ C_{\ell} & D_{\ell} \end{bmatrix} \right\|^{2} < +\infty, \tag{7}$$

where  $\|\cdot\|$  is an arbitrary matrix norm (whose particular choice is irrelevant in this case). The fulfillment of (7) allows the Fourier series

$$\begin{bmatrix} \mathsf{A}(\sigma) & \mathsf{B}(\sigma) \\ \mathsf{C}(\sigma) & \mathsf{D}(\sigma) \end{bmatrix} := \sum_{\ell \in \mathbb{Z}^{\mathsf{v}}} \mathrm{e}^{-i\ell^{\mathsf{T}}\sigma} \begin{bmatrix} A_{\ell} & B_{\ell} \\ C_{\ell} & D_{\ell} \end{bmatrix}, \tag{8}$$

to be defined (in a blockwise fashion) for almost all  $\sigma \in \mathbb{R}^{V}$  as the  $L^{2}$ -limit of appropriate partial sums over finite subsets of the lattice forming an exhausting sequence. Since the matrix-valued functions A, B, C, D (with values in  $\mathbb{C}^{n\times n}$ ,  $\mathbb{C}^{n\times m}$ ,  $\mathbb{C}^{r\times m}$ , respectively) are  $2\pi$ -periodic with respect to each of their arguments, then, without loss of generality, they can be considered on a v-dimensional torus  $\mathbb{T}^{v}$  (where  $\mathbb{T}$  can be identified with the interval  $[-\pi,\pi)$ ). These functions are Hermitian in the sense that  $\overline{A(\sigma)} = A(-\sigma)$  (and similarly for the other functions B, C, D) for all  $\sigma \in \mathbb{R}^{v}$ , where  $\overline{(\cdot)}$  is the complex conjugate. Furthermore, let  $\|u\|_{2} := \sqrt{\sum_{k \in \mathbb{Z}^{v}} |u_{k}|^{2}}$ ,  $\|x\|_{2} := \sqrt{\sum_{k \in \mathbb{Z}^{v}} |y_{k}|^{2}}$  denote the norms of the input, state and output of the network at a fixed but otherwise arbitrary moment of time  $t \geqslant 0$  in the corresponding Hilbert spaces

$$\mathfrak{U} := L^2(\mathbb{Z}^{\nu}, \mathbb{R}^m), \ \mathfrak{X} := L^2(\mathbb{Z}^{\nu}, \mathbb{R}^n), \ \mathfrak{Y} := L^2(\mathbb{Z}^{\nu}, \mathbb{R}^r)$$
(9)

of appropriately dimensioned square summable real vectorvalued functions  $f:=(f_k)_{k\in\mathbb{Z}^V}$  and  $g:=(g_k)_{k\in\mathbb{Z}^V}$  on the lattice  $\mathbb{Z}^V$  with the inner product  $\langle f,g\rangle:=\sum_{k\in\mathbb{Z}^V}f_k^{\mathsf{T}}g_k$ . Now, suppose the state-space matrices in (3) and (4) specify bounded linear operators  $A:\mathfrak{X}\to\mathfrak{X},\,B:\mathfrak{U}\to\mathfrak{X},\,C:\mathfrak{X}\to\mathfrak{Y},$  $D:\mathfrak{U}\to\mathfrak{Y}$ . This is equivalent to their  $L^2$ -induced operator norms being finite:

$$||A||_{\infty} = \underset{\sigma \in \mathbb{T}^{\nu}}{\operatorname{ess \, sup}} ||A(\sigma)|| < +\infty, \tag{10}$$

$$||B||_{\infty} = \operatorname*{ess\,sup}_{\sigma \in \mathbb{T}^{\nu}} ||B(\sigma)|| < +\infty, \tag{11}$$

$$||C||_{\infty} = \underset{\sigma \in \mathbb{T}^{\nu}}{\text{ess sup}} ||C(\sigma)|| < +\infty, \tag{12}$$

$$||D||_{\infty} = \operatorname{ess\,sup}_{\sigma \in \mathbb{T}^{\mathsf{v}}} ||\mathsf{D}(\sigma)|| < +\infty, \tag{13}$$

where the essential supremum is applied to the operator norms of the matrices in (8). In particular, if the matrices  $A_\ell$ ,  $B_\ell$ ,  $C_\ell$ ,  $D_\ell$  vanish for all  $\ell \in \mathbb{Z}^v$  with  $|\ell|$  large enough (so that each of the component systems in (1) and (2) is coupled with a finite number of the other systems in the network), then the functions A, B, C, D in (8) are multivariate trigonometric polynomials, and the conditions (10)–(13) are satisfied in this case. In general, the fulfillment of (10) and (11) guarantees that the operator exponential  $e^{tA}$  and the product  $e^{(t-\tau)A}B$  in (6) are bounded block Toeplitz operators acting on the Hilbert space  $\mathfrak X$  and from  $\mathfrak U$  to  $\mathfrak X$ , respectively, with

$$\|e^{tA}\|_{\infty} \leqslant e^{\|A\|_{\infty}t}, \qquad \|e^{(t-\tau)A}B\|_{\infty} \leqslant e^{\|A\|_{\infty}(t-\tau)}\|B\|_{\infty}$$
 (14)

for any  $t \ge \tau \ge 0$ , in view of the submultiplicativity of the operator norm and the fact that block Toeplitz matrices form an algebra. Therefore, if the initial network state is square summable, that is,

$$||x(0)||_2 < +\infty,$$
 (15)

and the network input is locally absolutely integrable with respect to time in the sense that

$$\int_{0}^{T} \|u(t)\|_{2} dt < +\infty, \qquad T > 0, \tag{16}$$

then these properties are inherited by the subsequent states of the network. Indeed, a combination of (6) with (14)–(16) leads to

$$||x(t)||_{2} \leq e^{||A||_{\infty}t} \left( ||x(0)||_{2} + ||B||_{\infty} \int_{0}^{t} ||u(\tau)||_{2} d\tau \right) < +\infty$$
(17)

for all  $t \ge 0$ , and hence,

$$\int_{0}^{T} \|x(t)\|_{2} dt \leq T e^{\|A\|_{\infty} T} (\|x(0)\|_{2} + \|B\|_{\infty} \int_{0}^{T} \|u(\tau)\|_{2} d\tau) < +\infty$$
 (18)

for any T > 0. Together with (4), (12), (13), the property (17) implies that the output norm  $||y(t)||_2$  is finite for almost all t > 0 since so is  $||u(t)||_2$  in view of (16). Furthermore, due to (18), the network output is also locally absolutely integrable with respect to time:

$$\int_{0}^{T} \|y(t)\|_{2} dt \leq \|C\|_{\infty} \int_{0}^{T} \|x(t)\|_{2} dt + \|D\|_{\infty} \int_{0}^{T} \|u(t)\|_{2} dt < +\infty$$
(19)

for any T > 0. In Section IV, we will replace (16) with a stronger condition on the network inputs in order to guarantee time-local square integrability for the outputs instead of (19).

## III. NETWORK DYNAMICS IN THE SPATIAL FREQUENCY DOMAIN

The preservation of the spatial square summability (17) (provided the input satisfies (16)) allows the network dynamics (3) and (4) to be represented in the spatial frequency domain as

$$\partial_t X(t, \sigma) = A(\sigma)X(t, \sigma) + B(\sigma)U(t, \sigma),$$
 (20)

$$Y(t,\sigma) = \mathsf{C}(\sigma)X(t,\sigma) + \mathsf{D}(\sigma)U(t,\sigma). \tag{21}$$

Here, similarly to (8), the functions U, X, Y on  $\mathbb{R}_+ \times \mathbb{T}^v$  with values in  $\mathbb{C}^m$ ,  $\mathbb{C}^n$ ,  $\mathbb{C}^r$  are the Fourier transforms of the input, state and output of the network:

$$U(t,\sigma) := \sum_{\ell \in \mathbb{Z}^{\mathcal{V}}} e^{-i\ell^{\mathrm{T}}\sigma} u_{\ell}(t), \tag{22}$$

$$X(t,\sigma) := \sum_{\ell \in \mathbb{Z}^{\mathcal{V}}} e^{-i\ell^{\mathsf{T}}\sigma} x_{\ell}(t), \tag{23}$$

$$Y(t,\sigma) := \sum_{\ell \subset \mathbb{Z}^{V}} e^{-i\ell^{\mathsf{T}}\sigma} y_{\ell}(t)$$
 (24)

for almost all  $\sigma \in \mathbb{T}^v$  at time  $t \ge 0$ . For any given  $\sigma$ , the equations (20) and (21) describe an autonomous system (which is independent of the other systems in this parametric family with different values of  $\sigma$ ) with a finite-dimensional internal state  $X(\cdot, \sigma)$ . Their solution can be represented in

terms of the Laplace transform over the time variable as

$$X(s,\sigma) := \int_0^{+\infty} e^{-st} X(t,\sigma) dt$$

$$= (sI_n - A(\sigma))^{-1} (X(0,\sigma) + B(\sigma)U(s,\sigma)), \qquad (25)$$

$$Y(s,\sigma) := \int_0^{+\infty} e^{-st} Y(t,\sigma) dt$$

$$= C(\sigma)X(s,\sigma) + D(\sigma)U(s,\sigma)$$

$$= C(\sigma)(sI_n - A(\sigma))^{-1} X(0,\sigma) + F(s,\sigma)U(s,\sigma), \quad (26)$$

where

$$U(s,\sigma) := \int_0^{+\infty} e^{-st} U(t,\sigma) dt.$$
 (27)

Here,

$$F(s,\sigma) := \mathsf{C}(\sigma)(sI_n - \mathsf{A}(\sigma))^{-1}\mathsf{B}(\sigma) + \mathsf{D}(\sigma) \tag{28}$$

is the spatio-temporal transfer function of the network with values in  $\mathbb{C}^{r \times m}$ . In view of (10), the relations (25)–(28) are valid for all  $s \in \mathbb{C}$  satisfying

Res > 
$$\max \left( \operatorname{ess\,sup} \ln \mathbf{r}(e^{\mathbf{A}(\sigma)}), \limsup_{t \to +\infty} \frac{\ln \|u(t)\|_2}{t} \right), \quad (29)$$

where  $\mathbf{r}(\cdot)$  denotes the spectral radius of a square matrix (so that  $\ln \mathbf{r}(e^N) = \max \operatorname{Re}\mathfrak{S}(N)$  is the largest real part of the eigenvalues of N, with  $\mathfrak{S}(N)$  denoting its spectrum). The presence of the upper limit in (29) makes the integral in (27) convergent in the Hilbert space  $L^2(\mathbb{T}^v,\mathbb{C}^m)$  due to the Parseval identity  $||U(t,\cdot)||_2 := \sqrt{\int_{\mathbb{T}^v} |U(t,\sigma)|^2 d\sigma} =$  $(2\pi)^{v/2}||u(t)||_2$  for any  $t \ge 0$ . In the case when the input vanishes, so that the network is effectively isolated from the environment, (20) reduces to a homogeneous linear ODE  $\partial_t X(t,\sigma) = A(\sigma)X(t,\sigma)$ . Its solution  $X(t,\sigma) =$  $e^{tA(\sigma)}X(0,\sigma)$ , considered for different values of  $\sigma \in \mathbb{T}^{\nu}$ , admits a direct analogy (formulated in system theoretic terms) with the phonon theory [13] of collective oscillations in spatially periodic arrangements of atoms in crystalline solids. More precisely, for a given  $\sigma \in \mathbb{T}^{\nu}$ , let  $z \in \mathbb{C}^n$  be an eigenvector of the matrix  $A(\sigma)$  associated with its eigenvalue  $s \in \mathbb{C}$ . Then the functions

$$x_k(t) = \operatorname{Re}(e^{st + ik^T\sigma}z), \qquad k \in \mathbb{Z}^{\nu}, \ t \geqslant 0,$$
 (30)

satisfy the ODEs (1) with u=0. Indeed, substitution of the latter equality and (30) into the right-hand side of (1) yields  $\sum_{k\in\mathbb{Z}^{V}}A_{j-k}x_{k}(t)=\operatorname{Re}\left(\mathrm{e}^{st+ij^{\mathrm{T}}\sigma}\sum_{k\in\mathbb{Z}^{V}}\mathrm{e}^{-i(j-k)^{\mathrm{T}}\sigma}A_{j-k}z\right)=\operatorname{Re}\left(\mathrm{e}^{st+ij^{\mathrm{T}}\sigma}A(\sigma)z\right)=\operatorname{Re}\left(\mathrm{se}^{st+ij^{\mathrm{T}}\sigma}z\right)=\dot{x}_{j}(t).$  For purely imaginary eigenvalues  $s=i\omega$  of the matrix  $A(\sigma)$  (with  $\omega\in\mathbb{R}$ ), the solutions (30) describe persistent oscillations of frequency  $\omega$  in the network, which are organised as (hyper) plane waves of length  $\frac{2\pi}{|\sigma|}$  in  $\mathbb{R}^{V}$ . Their wavefronts are orthogonal to the vector  $\sigma$  and move (along  $\sigma$ ) at constant phase velocity  $-\frac{\omega}{|\sigma|}$ , with the direction depending on the sign of  $\omega$ . Similarly to the dispersion relations of the phonon theory, the spectral structure of such oscillations in the network is represented by the multi-valued map  $\mathbb{T}^{V}\ni\sigma\mapsto\omega\in\mathbb{R}$  (of the wave vector to the frequency), which will be discussed in Section VI.

#### IV. SUPPLY RATE AND ENERGY BALANCE

A generalised model for the work done by the input u on the network is provided by a supply rate [18] at time  $t \ge 0$  in the form

$$S(t) := \langle u(t), Gy(t) \rangle = \sum_{j,k \in \mathbb{Z}^{\nu}} u_j(t)^{\mathrm{T}} G_{j-k} y_k(t)$$

$$= \frac{1}{(2\pi)^{\nu}} \int_{\mathbb{T}^{\nu}} U(t,\sigma)^* \mathsf{G}(\sigma) Y(t,\sigma) d\sigma$$

$$= \frac{1}{(2\pi)^{\nu}} \langle U(t,\cdot), \mathsf{G}Y(t,\cdot) \rangle, \tag{31}$$

where the Parseval identity is applied to the Fourier transforms U and Y from (22) and (24). The quantity S(t) is a bilinear function of the current input and output of the network which is specified by a block Toeplitz matrix  $G := (G_{j-k})_{j,k \in \mathbb{Z}^v}$ , where  $G_{\ell} \in \mathbb{R}^{m \times r}$  are given matrices satisfying

$$\sum_{\ell \in \mathbb{Z}^{\mathsf{V}}} \|G_{\ell}\|^2 < +\infty,\tag{32}$$

with the Fourier transform

$$\mathsf{G}(\sigma) := \sum_{\ell \in \mathbb{Z}^{\mathcal{V}}} \mathrm{e}^{-i\ell^{\mathrm{T}}\sigma} G_{\ell}. \tag{33}$$

It is assumed that the matrix G describes a bounded linear operator from the output space  $\mathfrak{Y}$  in (9) to the input space  $\mathfrak{U}$  in (9), so that

$$||G||_{\infty} = \operatorname{ess\,sup}_{\sigma \in \mathbb{T}^{\nu}} ||\mathsf{G}(\sigma)|| < +\infty, \tag{34}$$

similarly to the operator norms in (10)–(13). For example, the condition (34) holds in the case of a standard supply rate, when u and y consist of the corresponding force and velocity variables (with r = m) and G is the identity operator. Returning to the general case, substitution of (21) into (31) leads to

$$S(t) = \frac{1}{(2\pi)^{\nu}} \int_{\mathbb{T}^{\nu}} \operatorname{Re}(U(t,\sigma)^{*}\mathsf{G}(\sigma) \times (\mathsf{C}(\sigma)X(t,\sigma) + \mathsf{D}(\sigma)U(t,\sigma))) d\sigma$$

$$= \frac{1}{2(2\pi)^{\nu}} \int_{\mathbb{T}^{\nu}} Z(t,\sigma)^{*} \times \begin{bmatrix} 0 & \mathsf{C}(\sigma)^{*}\mathsf{G}(\sigma)^{*} \\ \mathsf{G}(\sigma)\mathsf{C}(\sigma) & \mathsf{G}(\sigma)\mathsf{D}(\sigma) + \mathsf{D}(\sigma)^{*}\mathsf{G}(\sigma)^{*} \end{bmatrix}$$

$$\times Z(t,\sigma) d\sigma. \tag{35}$$

where

$$Z(t,\sigma) := \begin{bmatrix} X(t,\sigma) \\ U(t,\sigma) \end{bmatrix} = \sum_{k \in \mathbb{Z}^{V}} e^{-ik^{T}\sigma} \begin{bmatrix} x_{k}(t) \\ u_{k}(t) \end{bmatrix}$$
(36)

is the Fourier transform of the augmented state-input pair of the network at time  $t \ge 0$ . Now, let  $V := (V_{j-k})_{j,k \in \mathbb{Z}^v}$  be a symmetric block Toeplitz matrix, which is specified by a square summable matrix-valued function  $\mathbb{Z}^v \ni \ell \mapsto V_\ell \in \mathbb{R}^{n \times n}$  on the lattice satisfying  $V_{-\ell} = V_\ell^T$ . Then the corresponding Fourier transform

$$V(\sigma) := \sum_{\ell \in \mathbb{Z}^{\nu}} e^{-i\ell^{\mathsf{T}} \sigma} V_{\ell}$$
 (37)

takes values in the subspace of complex Hermitian matrices of order n and satisfies

$$V(-\sigma) = V(\sigma)^{T} = \overline{V(\sigma)}, \qquad \sigma \in \mathbb{T}^{\nu}.$$
 (38)

Under the additional condition

$$||V||_{\infty} = \operatorname*{ess\,sup}_{\sigma \in \mathbb{T}^{V}} ||V(\sigma)|| < +\infty, \tag{39}$$

the matrix V describes a self-adjoint operator on the Hilbert space  $\mathfrak{X}$  in (9). This gives rise to a quadratic form of the network state at time  $t \ge 0$ :

$$H(t) := \frac{1}{2} \langle x(t), Vx(t) \rangle = \frac{1}{2} \sum_{j,k \in \mathbb{Z}^{V}} x_{j}(t)^{\mathrm{T}} V_{j-k} x_{k}(t)$$
$$= \frac{1}{(2\pi)^{V}} \int_{\mathbb{T}^{V}} \mathsf{H}(t,\sigma) \mathrm{d}\sigma, \tag{40}$$

where

$$\mathsf{H}(t,\sigma) := \frac{1}{2} X(t,\sigma)^* \mathsf{V}(\sigma) X(t,\sigma). \tag{41}$$

Here, the Parseval identity is applied to the Fourier transform X from (23), whose contribution to H(t) at a given  $\sigma \in \mathbb{T}^v$  is quantified by the real-valued quantity  $H(t,\sigma)$  in (41). The spatial frequency domain representation (20) of the network state dynamics allows the time derivative of H in (40) to be computed as

$$\dot{H}(t) = \frac{1}{(2\pi)^{\nu}} \int_{\mathbb{T}^{\nu}} \partial_{t} \mathsf{H}(t, \sigma) d\sigma, \tag{42}$$

with

$$\partial_{t} \mathsf{H}(t,\sigma) = \mathsf{Re} \big( X(t,\sigma)^{*} \mathsf{V}(\sigma) \partial_{t} X(t,\sigma) \big) 
= \mathsf{Re} \big( X(t,\sigma)^{*} \mathsf{V}(\sigma) (\mathsf{A}(\sigma) X(t,\sigma) + \mathsf{B}(\sigma) U(t,\sigma)) \big) 
= \frac{1}{2} Z(t,\sigma)^{*} \begin{bmatrix} \mathsf{A}(\sigma)^{*} \mathsf{V}(\sigma) + \mathsf{V}(\sigma) \mathsf{A}(\sigma) & \mathsf{V}(\sigma) \mathsf{B}(\sigma) \\ \mathsf{B}(\sigma)^{*} \mathsf{V}(\sigma) & 0 \end{bmatrix} Z(t,\sigma),$$
(43)

where use is made of (36). If H(t) in (40) describes the internal energy (usually referred to as the Hamiltonian) of the network at the current moment of time  $t \ge 0$ , then the difference

$$S(t) - \dot{H}(t) = \frac{1}{2(2\pi)^{\nu}} \int_{\mathbb{T}^{\nu}} Z(t, \sigma)^* N(\sigma) Z(t, \sigma) d\sigma \qquad (44)$$

can be interpreted as the energy dissipation rate. This quantity is part of the supply rate in (31) which is not accounted for by the rate of change of the internal energy in (42). The complex Hermitian matrix

$$N(\sigma) := \begin{bmatrix} -\mathsf{A}(\sigma)^*\mathsf{V}(\sigma) - \mathsf{V}(\sigma)\mathsf{A}(\sigma) \\ \mathsf{G}(\sigma)\mathsf{C}(\sigma) - \mathsf{B}(\sigma)^*\mathsf{V}(\sigma) \\ & \mathsf{C}(\sigma)^*\mathsf{G}(\sigma)^* - \mathsf{V}(\sigma)\mathsf{B}(\sigma) \\ \mathsf{G}(\sigma)\mathsf{D}(\sigma) + \mathsf{D}(\sigma)^*\mathsf{G}(\sigma)^* \end{bmatrix} \quad (45)$$

of order n+m in (44) is obtained by using (35), (42) and (43), and satisfies

$$N(-\sigma) = N(\sigma)^{\mathrm{T}} = \overline{N(\sigma)}, \qquad \sigma \in \mathbb{T}^{\nu},$$

similarly to (38). In order for the network model to correspond to a real physical system, the dissipation rate in

(44) has to be nonnegative in view of the total energy conservation, and hence,

$$S(t) \geqslant \dot{H}(t). \tag{46}$$

A sufficient condition for this inequality to hold for arbitrary admissible inputs u and initial network states x(0) is positive semi-definiteness of the matrix (45):

$$N(\sigma) \geq 0$$
, almost all  $\sigma \in \mathbb{T}^{\nu}$ . (47)

This condition is also necessary under an additional controllability assumption.

Theorem 1: Suppose the matrix pair  $(A(\sigma), B(\sigma))$  for the network in (1) and (2), given by (8), is controllable for any  $\sigma \in \mathbb{T}^{\nu}$ . Then the dissipation rate in (44) is nonnegative for any square summable initial network states and locally integrable inputs in (16) if and only if the matrix (45) satisfies (47).

If the self-adjoint operator V is positive semi-definite (which is equivalent to that the corresponding Fourier transform V in (37) satisfies  $V(\sigma) \geq 0$  for almost all  $\sigma \in \mathbb{T}^{\nu}$ ), and the network is initialized at zero state x(0) = 0, then the integration of both parts of (46) over a time interval [0,T] leads to

$$\int_{0}^{T} S(t) dt \ge H(T) - H(0) = H(T) \ge 0$$
 (48)

for any T > 0. These relations hold for any network input u such that  $||u(t)||_2$  is a locally square integrable function of time  $t \ge 0$  in the sense that

$$\int_0^T ||u(t)||_2^2 dt = \int_0^T \sum_{k \in \mathbb{Z}^V} |u_k(t)|^2 dt < +\infty, \qquad T > 0. \quad (49)$$

The condition (49) is stronger than (16) and guarantees finiteness of the work by such an input on the network over any bounded time interval. More precisely, (31) implies that

$$\left(\int_{0}^{T} |S(t)| dt\right)^{2} \leq \int_{0}^{T} ||u(t)||_{2}^{2} dt \int_{0}^{T} ||Gy(t)||_{2}^{2} dt$$

$$\leq ||G||_{\infty}^{2} \int_{0}^{T} ||u(t)||_{2}^{2} dt \int_{0}^{T} ||y(t)||_{2}^{2} dt \quad (50)$$

in view of the Cauchy-Bunyakovsky-Schwarz inequality and the boundedness (34) of the operator G. Here, the time-local square integrability of the input allows (19) to be enhanced

$$\frac{1}{2} \int_{0}^{T} \|y(t)\|_{2}^{2} dt \leq \int_{0}^{T} (\|Cx(t)\|_{2}^{2} + \|Du(t)\|_{2}^{2}) dt$$

$$\leq \|C\|_{\infty}^{2} \int_{0}^{T} \|x(t)\|_{2}^{2} dt + \|D\|_{\infty}^{2} \int_{0}^{T} \|u(t)\|_{2}^{2} dt, \qquad (51)$$

which is obtained by applying the inequality  $\frac{1}{2}\|\alpha + \beta\|^2 \le \|\alpha\|^2 + \|\beta\|^2$  in an arbitrary Hilbert space to the right-hand side of (4) and using the boundedness (12) and (13) of the operators C and D. Also, (17) implies that

$$||x(t)||_{2}^{2} \leq 2e^{2||A||_{\infty}t} \left( ||x(0)||_{2}^{2} + ||B||_{\infty}^{2} \left( \int_{0}^{t} ||u(\tau)||_{2} d\tau \right)^{2} \right)$$

$$\leq 2e^{2||A||_{\infty}t} \left( ||x(0)||_{2}^{2} + t||B||_{\infty}^{2} \int_{0}^{t} ||u(\tau)||_{2}^{2} d\tau \right), \quad (52)$$

where the Cauchy-Bunyakovsky-Schwarz inequality is used again. The local square integrability of  $\|x(t)\|_2$  as a function of time  $t \ge 0$  follows from (52) in view of (15) and (49). In combination with (51), this ensures the time-local square integrability of the network output:  $\int_0^T \|y(t)\|_2^2 dt < +\infty$  for any T > 0. From the last property, (49) and (50), it follows that the supply rate S(t) is indeed locally integrable with respect to time.

## V. NETWORK PASSIVITY CONDITIONS IN THE SPATIAL FREQUENCY DOMAIN

The relations (48) imply that the network is passive in the sense that any time-locally square integrable input u in (49) performs a nonnegative work:

$$W(T) := \int_0^T S(t) dt \ge 0, \qquad T > 0.$$
 (53)

The passivity can also be considered irrespective of a specific internal energy (storage) function (provided the initial network state is zero). For what follows, the network input u is assumed to be time-space square summable in the sense that

$$|||u||| := \sqrt{\int_0^{+\infty} ||u(t)||_2^2 dt} = \sqrt{\int_0^{+\infty} \sum_{k \in \mathbb{Z}^V} |u_k(t)|^2 dt} < +\infty,$$
(54)

where the norm  $\|\cdot\|$  is associated with the inner product  $\langle\!\langle f,g\rangle\!\rangle := \int_0^{+\infty} \langle f(t),g(t)\rangle = \int_0^{+\infty} \sum_{k\in\mathbb{Z}^V} f_k(t)^* g_k(t) \mathrm{d}t$  for real or complex vector-valued functions  $f(t) := (f_k(t))_{k\in\mathbb{Z}^V}$  and  $g(t) := (g_k(t))_{k\in\mathbb{Z}^V}$  of the time and space variables. By the Parseval identity, (54) yields  $\int_{\mathbb{R}\times\mathbb{T}^V} |\mathsf{U}(i\omega,\sigma)|^2 \mathrm{d}\omega \mathrm{d}\sigma = (2\pi)^{V+1} \|\|u\|\|^2$ , where the function U is given by (27). Although (54) is a stronger condition than (49), the input u produces the same work W(T) in (53) over a given time interval [0,T] as its "truncated" version

$$\Pi_T(u)(t) := \begin{cases} u(t) & \text{if } 0 \leqslant t \leqslant T \\ 0 & \text{otherwise} \end{cases}$$

(with  $\Pi_T$  being an orthogonal projection operator for any T > 0). This property follows from causality of the network as an input-output operator  $u \mapsto y$  and from the fact that the supply rate S(t) in (31) is a bilinear function of u(t) and y(t).

Theorem 2: Suppose the network, governed by (1) and (2), satisfies (7) and (10)–(13), and is endowed with the supply rate (31) subject to (32) and (34). Also, suppose the matrix  $A(\sigma)$  in (8) is Hurwitz for any  $\sigma \in \mathbb{T}^v$ . Then the network is passive in the sense of (53) for zero initial states and arbitrary time-locally square integrable inputs u in (49) if and only if its spatio-temporal transfer function (28) satisfies

$$E(\boldsymbol{\omega}, \boldsymbol{\sigma}) := F(i\boldsymbol{\omega}, \boldsymbol{\sigma})^* \mathsf{G}(\boldsymbol{\sigma})^* + \mathsf{G}(\boldsymbol{\sigma})F(i\boldsymbol{\omega}, \boldsymbol{\sigma}) \geq 0 \qquad (55)$$

for almost all  $(\omega, \sigma) \in \mathbb{R} \times \mathbb{T}^{\nu}$ . Here, the function G is given by (33).

Note that in the case of r = m and the standard supply rate mentioned above, G in (33) is the identity matrix, and (55) reduces to

$$F(i\omega, \sigma) + F(i\omega, \sigma)^* \geq 0, \qquad \omega \in \mathbb{R}, \ \sigma \in \mathbb{T}^{\nu},$$
 (56)

which is a network counterpart of the positive real property. On the other hand, in an extended setting, the block Toeplitz matrix G can be formed from differential operators  $G_{\ell}(\partial_t)$  with respect to time (whose entries are, for example, polynomials of  $\partial_t$ ). In this case, Theorem 2 is modified by replacing the function G in (55), given by (33), with the Fourier-Laplace transform

$$\mathsf{G}(s,\sigma) := \sum_{\ell \in \mathbb{Z}^{\mathcal{V}}} \mathrm{e}^{-i\ell^{\mathrm{T}}\sigma} G_{\ell}(s). \tag{57}$$

In particular, if r = m and the extended operator G acts on the network output as  $Gy = \dot{y}$ , then (57) yields  $G(s, \sigma) = sI_m$ . In accordance with the structure of the supply rate (31), this describes the setting when u and y consist of the corresponding force and position (rather than velocity) variables. In this case, (55) takes the form

$$i\omega(F(i\omega,\sigma)-F(i\omega,\sigma)^*) \geq 0, \qquad \omega \in \mathbb{R}, \ \sigma \in \mathbb{T}^{\nu}.$$
 (58)

Since the spatio-temporal transfer function F in (28) satisfies  $F(-i\omega, -\sigma) = \overline{F(i\omega, \sigma)}$  for all  $\omega \in \mathbb{R}$ ,  $\sigma \in \mathbb{R}^{\nu}$ , and the complex conjugation of a Hermitian matrix preserves positive semi-definiteness, then (58) is equivalent to

$$\frac{1}{i}(F(i\omega,\sigma) - F(i\omega,\sigma)^*) \leq 0, \qquad \omega \in \mathbb{R}_+, \ \sigma \in \mathbb{T}^{\nu}. \tag{59}$$

Similarly to (56), the condition (59) is a network version of the negative-imaginary property [10], [19]. In the case when the matrix  $A(\sigma)$  in (8) is Hurwitz for all  $\sigma \in \mathbb{T}^{\nu}$  (as assumed in Theorem 2), there exists a positive definite Hermitian  $\mathbb{C}^{n \times n}$ -valued function V in (37) on the torus  $\mathbb{T}^{\nu}$  satisfying (38), (39) and such that

$$A(\sigma)^*V(\sigma) + V(\sigma)A(\sigma) < 0, \qquad \sigma \in \mathbb{T}^{\nu}.$$
 (60)

In isolation from the environment (when u = 0), the quadratic stability of the network can be formulated by enhancing the positive definiteness as

$$\mu := \underset{\sigma \in \mathbb{T}^{\nu}}{\operatorname{ess}\inf} \lambda_{\min}(\mathsf{V}(\sigma)) > 0, \tag{61}$$

where  $\lambda_{\min}(\cdot)$  denotes the smallest eigenvalue. Then the corresponding block Toeplitz matrix V describes a positive definite self-adjoint operator on  $L^2(\mathbb{Z}^V,\mathbb{R}^n)$  whose inverse  $V^{-1}$  is also such an operator and its norm is related to the quantity  $\mu$  in (61) by

$$||V^{-1}||_{\infty} = \frac{1}{\mu}.$$
 (62)

Furthermore, the Hamiltonian H, associated with V by (40), admits the following bounds in terms of the standard  $L^2$ -norm of the network state:

$$\frac{\mu}{2} \|x(t)\|_2^2 \leqslant H(t) \leqslant \frac{\|V\|_{\infty}}{2} \|x(t)\|_2^2. \tag{63}$$

Similarly to finite-dimensional settings, the dissipativity (46) (or a nonstrict version of the inequality (60)) implies that the Hamiltonian of the isolated network does not increase with time (that is,  $\dot{H} \leq 0$ ), which, in combination with (63) leads to

$$||x(t)||_2^2 \le \frac{2}{\mu} H(t) \le \frac{2}{\mu} H(0) \le \frac{||V||_{\infty}}{\mu} ||x(0)||_2^2, \quad t \ge 0 \quad (64)$$

(similar bounds, arising from quadratic Hamiltonians, are also used for quantum harmonic oscillators [9, Eq. (22)]). In view of (62), the factor  $\frac{\|V\|_{\infty}}{\mu} = \|V\|_{\infty} \|V^{-1}\|_{\infty} \geqslant 1$  on the right-hand side of (64) is the condition number of the operator V (which quantifies how far V is from scalar operators).

### VI. PHONON THEORETIC DISPERSION RELATIONS

We will now consider a class of translation invariant networks, which, in isolation from the environment, manifest phonon-like dynamics mentioned in Section III. Suppose the state vectors  $x_k$  of the component systems consist of the conjugate position and momentum variables which are assembled into  $\frac{n}{2}$ -dimensional vectors  $q_k$  and  $p_k$ , respectively (with n being even):

$$x_k = \begin{bmatrix} q_k \\ p_k \end{bmatrix}, \qquad k \in \mathbb{Z}^{\mathbf{v}}. \tag{65}$$

Accordingly, the network is assumed to have the following Hamiltonian:

$$H := \frac{1}{2} \sum_{j \in \mathbb{Z}^{\nu}} \left( \|p_j\|_{M^{-1}}^2 + q_j^{\mathsf{T}} \sum_{k \in \mathbb{Z}^{\nu}} K_{j-k} q_k \right). \tag{66}$$

Here, M is a real positive definite symmetric mass matrix of order  $\frac{n}{2}$ , and use is made of a weighted Euclidean norm  $\|v\|_L := \sqrt{v^T L v} = |\sqrt{L}v|$  of a vector v specified by such a matrix L. Also,  $K := (K_{j-k})_{j,k \in \mathbb{Z}^v}$  is a symmetric block Toeplitz stiffness operator whose blocks  $K_\ell \in \mathbb{R}^{\frac{n}{2} \times \frac{n}{2}}$  specify the potential energy part of the Hamiltonian. In view of (65) and (66), the blocks of the corresponding block Toeplitz matrix V in (40) are given by

$$V_{\ell} = \begin{bmatrix} K_{\ell} & 0\\ 0 & \delta_{0\ell} M^{-1} \end{bmatrix}, \qquad \ell \in \mathbb{Z}^{\nu}, \tag{67}$$

where  $\delta_{jk}$  is the Kronecker delta. In application to the isolated network, the Hamiltonian equations of motion take the form

$$\dot{x}_{j} = \begin{bmatrix} \dot{q}_{j} \\ \dot{p}_{j} \end{bmatrix} = J \partial_{x_{j}} H = \begin{bmatrix} \partial_{p_{j}} H \\ -\partial_{q_{i}} H \end{bmatrix} = \begin{bmatrix} M^{-1} p_{j} \\ -\sum_{k \in \mathbb{Z}^{v}} K_{j-k} q_{k} \end{bmatrix}$$
(68)

for all  $j \in \mathbb{Z}^{\nu}$ , where

$$J := \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \otimes I_{n/2} \tag{69}$$

is the symplectic structure matrix associated with the partitioning (65), with  $\otimes$  the Kronecker product of matrices. A comparison of (68) with (1) allows the blocks of the matrix A in (3) to be expressed in terms of (67) and (69) as

$$A_{\ell} = JV_{\ell} = \begin{bmatrix} 0 & \delta_{0\ell} M^{-1} \\ -K_{\ell} & 0 \end{bmatrix}, \qquad \ell \in \mathbb{Z}^{\nu}. \tag{70}$$

Upon substituting (70) into (8), the function A takes the form

$$A(\sigma) = \begin{bmatrix} 0 & M^{-1} \\ -K(\sigma) & 0 \end{bmatrix}, \tag{71}$$

where

$$\mathsf{K}(\sigma) := \sum_{\ell \in \mathbb{Z}^{\mathsf{v}}} \mathrm{e}^{-i\ell^{\mathsf{T}}\sigma} K_{\ell}. \tag{72}$$

Since  $M \succ 0$ , then  $s \in \mathbb{C}$  is an eigenvalue of the matrix A( $\sigma$ ) in (71) if and only if  $s^2$  is an eigenvalue of  $-M^{-1/2}K(\sigma)M^{-1/2}$ . Therefore, if the stiffness operator K is positive semi-definite (so that 0 delivers a minimum to the potential energy), then  $A(\sigma)$  has a purely imaginary spectrum:

$$\mathfrak{S}(\mathsf{A}(\sigma)) = \left\{ \pm i\sqrt{\lambda} : \lambda \in \mathfrak{S}(\mathsf{K}(\sigma)M^{-1}) \right\}$$
 (73)

for any  $\sigma \in \mathbb{T}^{\nu}$ . Such a network is organised as an infinitedimensional spring-mass system whose vibrations are linear superpositions of "basis" phonons given by (30) with  $s=\pm i\sqrt{\lambda}$  for different values of  $\sigma\in\mathbb{T}^{\nu}$ . The matrix  $\mathsf{K}(\sigma)M^{-1}=\sqrt{M}M^{-1/2}\mathsf{K}(\sigma)M^{-1/2}M^{-1/2}$  in (73), which is isospectral to  $M^{-1/2}\mathsf{K}(\sigma)M^{-1/2}\succcurlyeq 0$ , corresponds to the stiffness-to-mass ratio for one-mode harmonic oscillators. The dynamic properties of phonons with large wavelengths  $\frac{2\pi}{|\sigma|}$  (manifesting themselves in highly correlated motions of distant subsystems in the network) depend on the asymptotic behaviour of the matrix  $K(\sigma)$  in (72) in a small neighbourhood of  $\sigma = 0$ .

Theorem 3: Suppose the isolated translation invariant network (68) with the Hamiltonian (66) has a positive semidefinite stiffness operator K satisfying

$$\sum_{\ell=77} K_{\ell} = 0, \tag{74}$$

$$\sum_{\ell \in \mathbb{Z}^{\mathbf{v}}} K_{\ell} = 0, \tag{74}$$

$$\sum_{\ell \in \mathbb{Z}^{\mathbf{v}}} |\ell|^{2} ||K_{\ell}|| < +\infty. \tag{75}$$

Then the phase velocities of the phonons in the network are uniformly bounded:

$$\sup \left\{ \frac{\omega}{|\sigma|} : \ \sigma \in \mathbb{T}^{\nu} \setminus \{0\}, \ \omega \in \mathbb{R}_{+}, i\omega \in \mathfrak{S}(\mathsf{A}(\sigma)) \right\} < +\infty.$$

$$(76)$$

The property (76) is based substantially on the asymptotic behaviour of  $\mathbf{r}(A(\sigma))$  as  $\sigma \to 0$ , which corresponds to longwave phonons. The speed of propagation of disturbances is described in physics literature in terms of their group velocity  $\partial_{\sigma}\omega$  (see, for example, [6]). The differentiability is ensured for those phonons whose frequency  $\omega$  corresponds to a non-degenerate eigenvalue (of multiplicity one [4], [5]) of the matrix  $K(\sigma)M^{-1}$  in (73), with the function K in (72) being twice continuously differentiable due to (75). We will now provide an example which illustrates the condition (74). Consider the movement of a thin isotropic plate of density  $\rho > 0$  and bending stiffness  $\beta > 0$ , governed by the Kirchhoff-Love equation [11]:

$$\rho \partial_t^2 w = -\frac{\beta}{2} \Delta^2 w + f. \tag{77}$$

Here,  $w(t,\xi)$  is the local deviation of the plate from the equilibrium (unbent) position, which is a real-valued function of time t and the two-dimensional vector  $\boldsymbol{\xi} := \begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix} \in \mathbb{R}^2$ of Cartesian coordinates on the plane, and  $\Delta := \partial_{\mathcal{E}_1}^2 + \partial_{\mathcal{E}_2}^2$ is the Laplacian over the spatial variables. Also,  $f(t,\xi)$ is the density of the external force acting transversally

on the plate. A finite-difference scheme for the numerical solution of the PDE (77) with spatial step size h > 0 can be viewed as a translation invariant network on the twodimensional integer lattice  $\mathbb{Z}^2$ . By denoting  $\mathfrak{V} := (\mathfrak{V}_{ik})_{i,k\in\mathbb{Z}}$ the spatial discretization of the solution of (77) at time  $t \ge 0$ (so that  $\mho_{ik}(t)$  approximates w(t, jh, kh)), the corresponding functions

$$q := \mho, \qquad p := \rho \partial_t \mho$$
 (78)

on the set  $\mathbb{R}_+ \times \mathbb{Z}^2$  are evolved according to the Hamilton equations

$$\dot{q} = \frac{1}{\rho}p, \qquad \dot{p} = -\frac{\beta}{2}L^2q + g.$$
 (79)

Here,  $g := (f(t, jh, kh))_{j,k \in \mathbb{Z}}$  is a discretization of the forcing term, and L is a self-adjoint Toeplitz operator which approximates the Laplacian  $\Delta$  as

$$(L\mathfrak{V})_{jk} := \frac{1}{h^2} (q_{j+1,k} + q_{j-1,k} + q_{j,k+1} + q_{j,k-1} - 4q_{jk}). \tag{80}$$

A comparison of (78) and (79) with (68) shows that the scalar  $\rho$  plays the role of the mass matrix M, and  $\frac{\beta}{2}L^2$  is the stiffness operator K. The latter implies that the Fourier transforms (72) and  $L(\sigma) := \sum_{\ell \in \mathbb{Z}^2} e^{-i\ell^T \sigma} L_\ell$  are related by  $K = \frac{\beta}{2}L^2$ , and hence, K inherits the property (74) from the discretized Laplacian L in (80), since  $L(0) = \sum_{\ell \in \mathbb{Z}^2} L_{\ell} = 0$ .

#### VII. CONCLUSION

We have considered a class of translation invariant networks of interacting linear systems at sites of a multidimensional lattice. Energy-based input-output properties of such a network (including passivity, positive realness and the negative imaginary property) have been considered in terms of its transfer function representation in the spatio-temporal frequency domain. We have also discussed quadratic stability of the network in the isolated regime, and dispersion relations for phonons in the isolated network. The results of the paper are applicable to quadratic regulation problems for large flexible structures with a sparse collocation of sensors and actuators. In the spatially discrete network setting, the technical side of such problems is more simple than control design for distributed parameter systems governed by PDEs [2], [3].

### **ACKNOWLEDGEMENT**

Comments of the anonymous reviewer, including the references [2], [3], are gratefully acknowledged.

### REFERENCES

- [1] B.Bamieh, F.Paganini, and M.A.Dahleh, Distributed control of spatially invariant systems, IEEE Trans. Autom. Contr., vol. 47, no. 7, 2002, pp. 1091-1107.
- [2] R.Curtain, Comments on "Distributed control of spatially invariant systems", IEEE Trans. Autom. Contr., vol. 56, no. 3, 2011, pp. 707-
- R.Curtain, O.Iftime, and H.Zwart, A comparison between LQR control for a long string of SISO systems and LQR control of the infinite spatially invariant version, Automatica, vol. 46, no. 10, 2010, pp.
- [4] N.J.Higham, Functions of Matrices, SIAM, 2008.
- [5] R.A.Horn, and C.R.Johnson, Matrix Analysis, Cambridge University Press, New York, 2007.

- [6] L.D.Landau, and E.M.Lifshitz, Statistical Physics, 3rd Ed., Butterworth-Heinemann, Oxford, 1980.
- [7] R.Ortega, A.J.van der Schaft, I.Mareels, and B.Maschke, Putting energy back in control, *IEEE Contr. Sys.*, vol. 21, no. 2, pp. 18–33, 2001.
- [8] R.Ortega, A.van der Schaft, B.Maschke, and G.Escobar, Interconnection and damping assignment passivity-based control of port-controlled Hamiltonian systems, *Automatica*, vol. 38, no. 4, 2002, pp. 585–596.
- [9] I.R.Petersen, A direct coupling coherent quantum observer, 2014 IEEE Conference on Control Applications (CCA), 8–10 October 2014 (arXiv:1408.0399v2 [quant-ph], 8 August 2014).
- [10] I.R.Petersen, and A.Lanzon, Feedback control of negative-imaginary systems, *IEEE Contr. Sys.*, vol. 30, no. 5, 2010, pp. 54–72.
- [11] J.N.Reddy, Theory and Analysis of Elastic Plates and Shells, 2nd Ed., CRC Press, Taylor and Francis, London, 2007.
- [12] A.Kh.Sichani, I.G.Vladimirov, and I.R.Petersen, Covariance dynamics and entanglement in translation invariant linear quantum stochastic networks IEEE 54th Annual Conference on Decision and Control (CDC), December 15-18, 2015, Osaka, Japan, pp. 7107–7112.
- [13] G.P.Srivastava, The Physics of Phonons, Taylor & Francis, 1990.
- [14] A. van der Schaft, and D. Jeltsema, Port-Hamiltonian Systems Theory: An Introductory Overview, *Foundations and Trends R in Systems and Control*, vol. 1, no. 2–3, 2014, pp. 173–378.
- [15] V.Veselago, L.Braginsky, V.Shklover, and C.Hafner, Negative refractive index metamaterials, *J. Comp. Theor. Nanosci.*, vol. 3, 2006, pp. 1–30.
- [16] I.G.Vladimirov, and I.R.Petersen, Physical realizability and mean square performance of translation invariant networks of interacting linear quantum stochastic systems, 21st Int. Symp. Math. Theor. Networks Syst., Groningen, The Netherlands, July 7–11, 2014, pp. 1881–1888.
- [17] I.G.Vladimirov, and I.R.Petersen, Spatio-temporal transfer function conditions of positive realness for translation invariant lattice networks of interacting linear systems, arXiv:1802.00185 [cs.SY], 1 February 2018.
- [18] J.C.Willems, Dissipative dynamical systems. Part I: general theory, Part II: linear systems with quadratic supply rates, Arch. Rational Mech. Anal., vol. 45, no. 5, 1972, pp. 321–351, 352–393.
- [19] J.Xiong, I.R.Petersen, and A.Lanzon, A negative imaginary lemma and the stability of interconnections of linear negative imaginary systems, *IEEE Trans. Automat. Contr.*, vol. 55, no. 10, 2010, pp. 2342–2347.